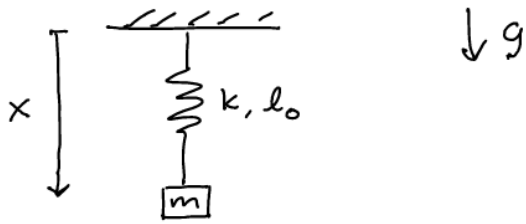


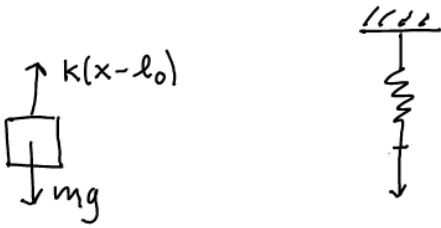
Föreläsning 7, mekanik del 1

Svängningar

Fri odämpad svängning



Frilägg:



Newton II:

$$\downarrow: mg - k(x - l_0) = m\ddot{x} \Leftrightarrow \ddot{x} + \underbrace{\frac{k}{m}}_{\omega_n^2} x = g + \frac{kl_0}{m} \quad (1)$$

ω_n : egen vinkel frekvens

$$x = x_h + x_p$$

Homogenlösning x_h :

$$x_h = A \cos(\omega_n t) + B \sin(\omega_n t)$$

Partikulärlösning, x_p

$$x_p = C, \text{ konst}$$

$$(1) \Rightarrow \frac{k}{m} c = g + \frac{k l_0}{m} \Leftrightarrow c = \frac{mg}{k} + l_0$$

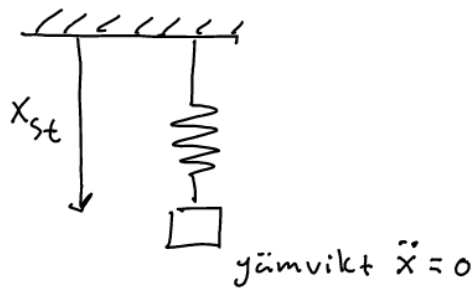
$$\therefore x = A \cos(\omega_n t) + B \sin(\omega_n t) + \frac{mg}{k} + l_0$$

Bestäm A och B ur givna värden på $x(0)$ och $\dot{x}(0)$

Svängningstid T_n :

$$\omega_n T_n = 2\pi \Leftrightarrow T_n = \frac{2\pi}{\omega_n}$$

Bestämning av jämviktsläge, x_{st} .



$$(1) \Rightarrow \frac{k}{m} x_{st} = g + \frac{k l_0}{m} \Leftrightarrow x_{st} = l_0 + \frac{mg}{k}$$

Fri dämpad svängning

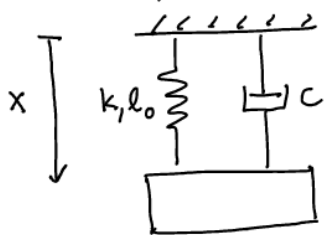
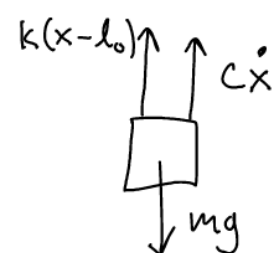


Fig 1.



Newton II:

$$\downarrow : mg - k(x - l_0) - c\dot{x} = m\ddot{x} \Leftrightarrow \ddot{x} + \underbrace{\frac{c}{m}}_{2\zeta\omega_n} \dot{x} + \underbrace{\frac{k}{m}}_{\omega_n^2} x = g + \frac{kl_0}{m} \quad (2)$$

ζ dämpfaktor.

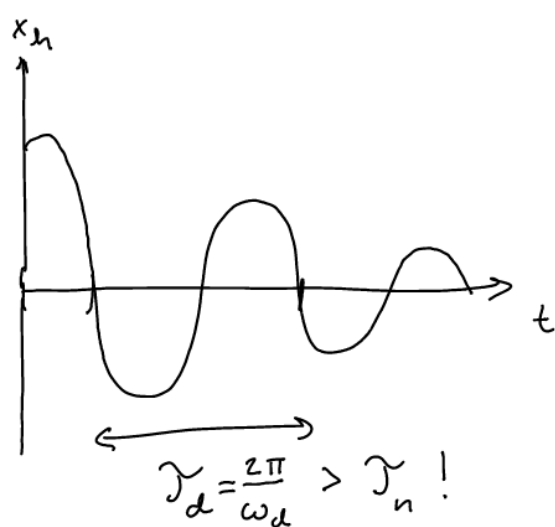
↑
grekiskt
 ζ

$$x = x_h + x_p$$

$\zeta < 1$: underdämpat system.

$$\boxed{x_h = e^{-\zeta\omega_n t} (A\cos\omega_d t + B\sin(\omega_d t))}$$
$$\omega_d = \sqrt{1 - \zeta^2}$$

ω_d : dämpad egenvinkelfrekvens

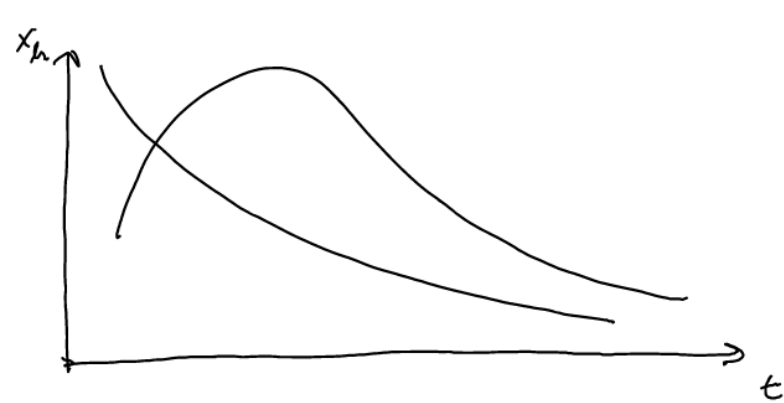


Fortvarighet: x_h , dvs $x = x_p$

Lösning oberoende av begynnelsevillkoren!

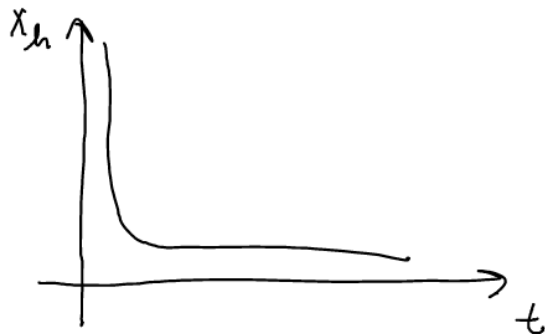
$\zeta > 1$: överdämpat system

$$x_h = A \cdot e^{-(\zeta - \sqrt{\zeta^2 - 1})\omega_n t} + B e^{-(\zeta + \sqrt{\zeta^2 - 1})\omega_n t}$$



$\zeta = 1$: Kritiskt dämpat system.

$$x_h = (A + Bt)e^{-\omega_n t}$$



Konvergerar snabbare
än för överdämpat!

Ex Fig 1

Givet; k, m

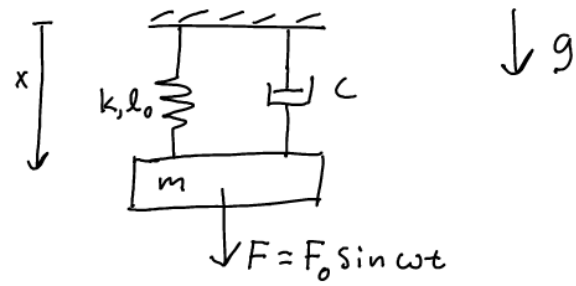
$$\zeta = 1$$

Söker c .

$$(2) \Rightarrow 2\zeta\sqrt{\frac{k}{m}} = \frac{c}{m} \Leftrightarrow c = 2\sqrt{mk}$$



Påtvångad, dämpad svängning



Newton II:

$$\downarrow: mg - k(x - l_0) - c\dot{x} + F_0 \sin \omega t = m\ddot{x}$$

$$\Leftrightarrow \ddot{x} + \underbrace{\frac{c}{m}}_{2\zeta\omega_n} \dot{x} + \underbrace{\frac{k}{m}}_{\omega_n^2} x = g + \frac{kl_0}{m} + \frac{F_0}{m} \sin \omega t \quad (3)$$

$$x = x_h + x_p$$

vid fortvarighet: $x = x_p$ ($x_h = 0$)

$$x_p = \bar{x}_1 + \underbrace{\bar{x}_2 \sin \omega t + \bar{x}_3 \cos \omega t}_{=0 \text{ om } \zeta=0} \quad (\text{odämpat})$$

$$\dot{x}_p = \bar{x}_2 \omega \cos \omega t - \bar{x}_3 \omega \sin \omega t$$

$$\ddot{x}_p = -\bar{x}_2 \omega^2 \sin \omega t - \bar{x}_3 \omega^2 \cos \omega t$$

Ins i (3) \Rightarrow

$$-\bar{x}_2 \omega^2 \sin \omega t - \bar{x}_3 \omega^2 \cos \omega t + \frac{c}{m} (\bar{x}_2 \omega \cos \omega t - \bar{x}_3 \omega \sin \omega t) +$$

$$+ \frac{k}{m} (\bar{x}_1 + \bar{x}_2 \sin \omega t + \bar{x}_3 \cos \omega t) =$$

$$g + \frac{kl_0}{m} + \frac{F_0}{m} \sin \omega t$$

Identifera koefficienter:

$$\text{konst: } \frac{k}{m} \bar{x}_1 = g + \frac{k l_0}{m}$$

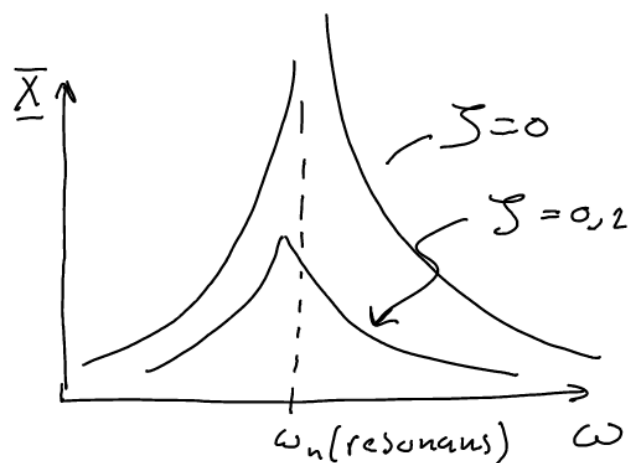
$$\sin \omega t: -\bar{x}_2 \omega^2 - \frac{c}{m} \bar{x}_3 \omega + \frac{k}{m} \bar{x}_2 = \frac{F_0}{m}$$

$$\cos \omega t: -\bar{x}_3 \omega^2 + \frac{c}{m} \bar{x}_2 \omega + \frac{k}{m} \bar{x}_3 = 0$$

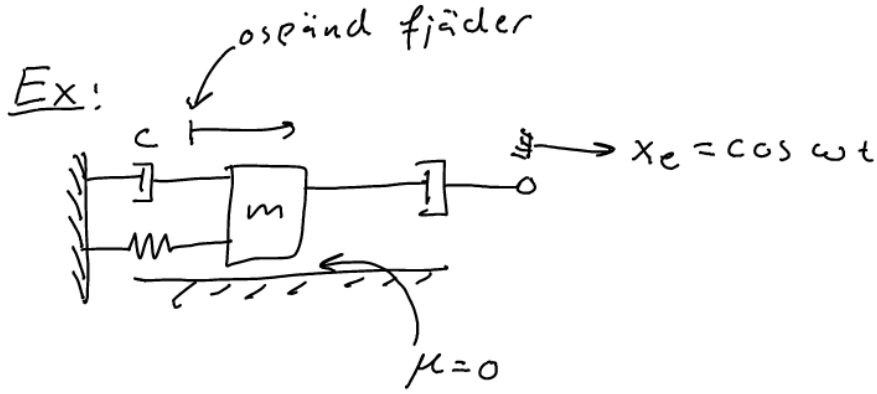
$$\Rightarrow \bar{x}_1, \bar{x}_2, \bar{x}_3$$

kan skriva

$$x_p = \bar{x}_1 + \underbrace{\bar{X}}_{\substack{\uparrow \\ \text{amplitud} \\ (= \sqrt{\bar{x}_2^2 + \bar{x}_3^2})}} \sin(\omega t + \underbrace{\varphi}_{\substack{\uparrow \\ \text{fasvinkel}}})$$

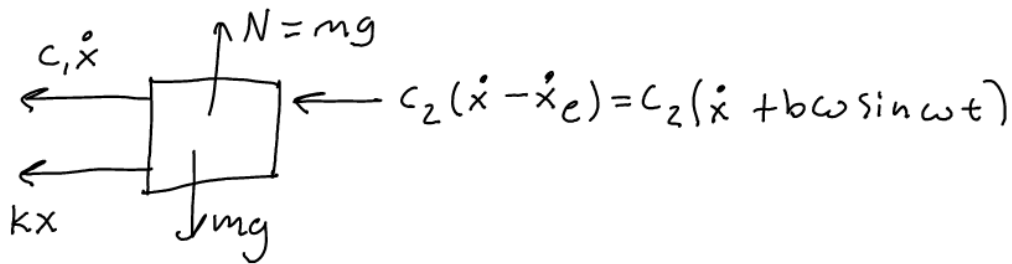


ω stor $\Rightarrow \bar{X}$ liten.



Diff eku!

Frilägg:



$$\rightarrow: -kx - c_1 \dot{x} - c_2 (\dot{x} + b\omega \sin \omega t) = m \ddot{x}$$

$$\Leftrightarrow \ddot{x} + \underbrace{\frac{c_1 + c_2}{m}}_{2\beta\omega_n} \dot{x} + \underbrace{\frac{k}{m}}_{\omega_n^2} x = - \frac{c_2 b \omega}{m} \sin \omega t$$

